# DE-FOA-0000026 - Grant Supporting Construction of United States Based Manufacturing Plants to Produce Electric Drive Components

**Poster Title: Electric Drive Component Manufacturing** 

**Project ID: ARRAVT027** 

Janice Thomas, Principal Investigator

#### Brian K. Peaslee, Presenter

Propulsion Systems Chief Engineer Magna Electronics 1955 Enterprise Drive Rochester Hills, MI 48309

#### **Team members:**

Magna E-Car Systems of America, Inc. Magna E-Car USA, Limited Partnership

Project Duration: 1 July 2010 to 30 June 2014

2012 DOE Vehicle Technologies Program Annual Merit Review Arlington, Virginia

May 14, 2013





### **Overview**

#### **Timeline**

- Start Date: July 1, 2010
- End Date: June 30, 2014
- More than 50% Complete

### **Budget**

- Total Project Funding
  - DOE \$40,000,000
  - Magna E-Car \$47,402,116
- DOE Funding
  - FY2010: \$ 7,821,414
  - FY2011: \$ 14,038,417
  - FY2012: \$ 7,665,051
  - FY2013: \$ 787,577

#### **Barriers**

- Reduction in expected market demand has resulted in delays to planned capacity growth, equipment purchases, equipment installation and validation activities to balance production capacity to customer orders. The project was extended to accommodate slowed production capacity growth rate.
- Reduced market demand increasing cost and timing for unique lowvolume components.

#### **Partners**

- Magna E-Car USA, LP
- Magna Powertrain USA, Inc.
- VEHMA International of America, Inc.

## **FY2013 Milestones**

#### Overall Milestone Status

- All programs continue to follow Program Management Plan timing with minimal delays
- PPAP of mid-cycle enhancements (Job#2) April 2013
- Deliver quality product to production releases

| Component             | Milestone   | Start Date | End<br>Date | %<br>Complete |
|-----------------------|---|------------|-------------|---------------|
| PCM & TCM             | Software Development – Job #2                           | 12/10/12   | 3/18/13     | 95%           |
| PCM & TCM             | PPAP Activities for Mid-Cycle Enhancements – Job #2     | 11/16/12   | 3/27/13     | 90%           |
| PCM & TCM             | 2013/14 Job #2 – Powertrain Phase (PP)                  | 3/4/13     |             | 100%          |
| PCM & TCM             | 2013/14 Job #2 – Tooling Trial (TT)                     | 4/23/13    |             | 0%            |
| Hybrid<br>Controller  | Production Part Approval Process (PPAP)                 | 2/12/12    | 1/18/13     | 100%          |
| Hybrid<br>Controller  | Production Readiness to Start of Production             | 1/18/13    | 4/29/13     | 10%           |
| Battery<br>Controller | Design Validation (DV) – Build, Test, & Analysis        | 11/30/12   | 6/13/13     | 50%           |
| Battery<br>Controller | Production Line Equipment – Kick-off, Procure & Install | 4/17/13    | 11/20/13    | 0%            |

## Relevance

### **Project Objectives**

- Increase production capacity and validate production capability of advanced automotive electric drive component manufacturing plants in the U.S.
  - Completion of the activities required to manufacture and supply electric drive systems to existing OEM customer projects supporting long-term economic growth
  - Creation and validation of production capability of advanced automotive electric drive vehicle components for electric vehicle production programs in the U.S. spurring economic activity
  - Preparation of a newly acquired facility to house the manufacturing activities that are supported by this project creating new engineering and manufacturing jobs

### 2013 Objectives

- Validation Mid-Cycle Enhancements for model year production, 2013-14, (Job #2)
- Implement software feature additions for Job #2 activity on BEV platform
- Launch Mid-Cycle Enhancements for model year production, 2013-14, (Job #2)
- Install required production capacity for new hybrid control module
- Continue Battery Control Module & Cell Sense Board development on HEV program
- Procure production equipment for battery control module & Cell Sense Board

# Summary of Accomplishments and Progress – FY2012

## **Development & Manufacturing**

**PowerPlant System (MCU and Motor)** 

- Production launched delivered 2096 PowerPlant Assy's
- Production launched delivered 4352 Stand alone Inverters

**Vehicle Control Unit (VCU)** 

- Production launched delivered 1617 Controllers
   Battery Charger Converter Module (BCCM)
- Gamma level design prototypes integrated into vehicles Integrated Chassis Control Module (ICCM)
- Completion of production verification (PV) testing
- Achieved Production Run at Rate and completed PPAP Battery Management System
- DV testing of BSM and CSB

Vehicle Systems – Electric Powertrain Assy & Vehicle Integration

- Production launched delivered 1897 Assy's
- On-going production support to OEM













## **Progress: 2012 GBEV Production Launch**

**Motor & Inverter** 

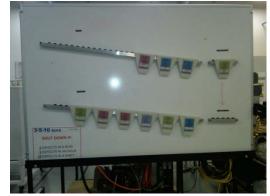
#### Production Actions

- > Inventory management
- Visual Production Scheduling
- Improved Pack-out process
- > Returnable Dunnage

















## Progress: GBEV 2012 Additions High Volume Inverter & Quality Lab

Capacity: 45k/year, Expandable to 135K





Housing and connector assembly



IGBT, capacitor, DC bus bar installation



Sub assemblies and gate drive board mounting



AC bus bar, control board, X-Y Filter board mounting



Hi-pot and final function tester



Housing and cover sealing



Vent plug and shipping caps installation



**GBEV Quality Lab** 

Controlled Crib
Coordinate
Measurement Machine
(CMM) Diagnostic lab
with controlled

## **Accomplishment: Battery Management System (BMS) – New Production Program**



#### Description

 The Battery Management Systems monitors and controls the high voltage battery system in EV, PHEV, and HEV's. The BMS performs all measurements and controls to determine SOC, SOH, and operates as a safety critical system to protect the battery system from over charge and over discharge.

#### Features/Specifications

- Communication with up to 20 external cell sensing devices
- Control of isolation devices (contactors) for Pack +, Pack -, and charging connections
- Support for J1772 charging interface
- Measurement of pack and link high voltage
- Isolation / Dielectric breakdown detection between pack and 12V vehicle systems
- Redundant microprocessor for parallel calculation and safety
- Thermal controls for fans and temperature monitoring
- Flexible multi-function I/O



#### Key Benefits



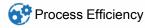
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## **Accomplishment: Developed Battery Cell Sensing Board (CSB) – New Production Program**



#### Description

The **CSB** measures individual cell voltages, module group voltages, and temperatures for a HEV or BEV battery. All cell voltages and module temperatures are reported directly to a Battery Management System (BMS). The CSB also performs internal circuit diagnostics and cell balancing.

#### Features/Specifications

- Cell balancing capable up to 50mA, limited due to housing
- 12 Cell voltage measurement
- Sampling every 3ms
- Accuracy to +/- 0.001V @ 25C
- Accuracy to +/- 0.003V @ -40C to 85C
- Sampling synchronization with all other modules
- <25uA current draw from cells</li>



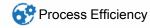
#### Key Benefits



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## **Accomplishment: Developed High Content Integrated Chassis Control Module (ICCM)**



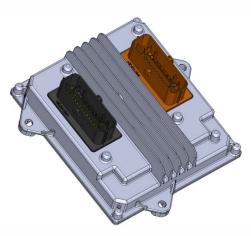
#### Description

 The ICCM is used on both conventional gasoline vehicles as well as HEV's. The module provides safety critical hardware with multi-function I/O that can be adapted by software for multiple vehicle applications.

#### Features/Specifications

- Operation between 6V and 16VDC
- 6 high current high side drives capable of on/off or PWM up to 2kHz
- 16 high current low side drives capable of on/off or PWM up to 2kHz
- 6 low side low current outputs
- 6 analog inputs for 0-5V sensor measurement
- 3 digital inputs for 12V signals
- Sampling synchronization with all other modules
- Redundant microprocessor for parallel calculation and safety





#### Key Benefits



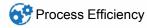
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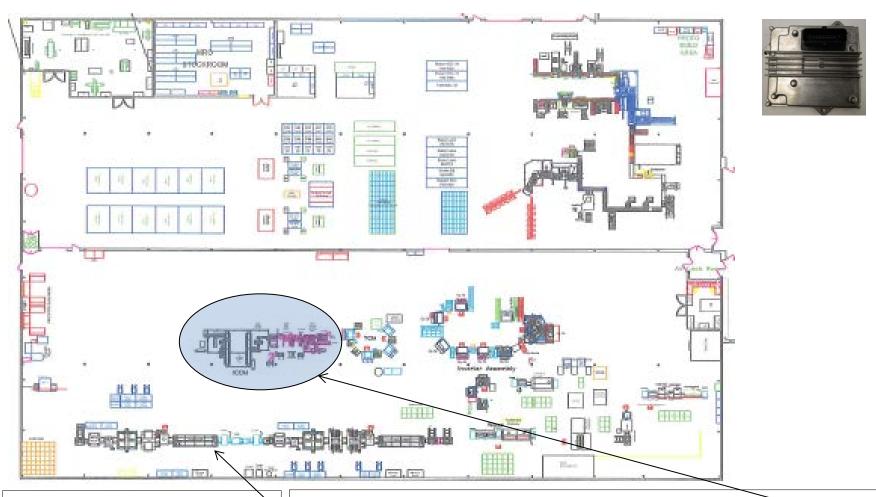


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# **Approach: Install High Volume Hybrid Controller Assembly Line**



Initial Volume: 400K/year Peak capacity: ~800k/year

Automated Final Assembly Cell for High Volume Controller
Utilize Printed Circuit Boards Capacity on existing SMD lines

Approach: Manufacturing Process with Highly Automated Final Assembly .



Final Assembly Cell Connector, PCB & Housing, Auto press connector to board & inspect

**Connector & housing sealing surface treatment** 



**Sealant & Thermal Gel Dispense 100% Machine Vision Inspection** 



Place housing and drive fasteners to attach PCB to housing, 100% torque/angle control



## **Approach: Manufacturing Process with Highly Automated Final Assembly**



Robotic placement: housing, fasteners, 100% torque & angle control



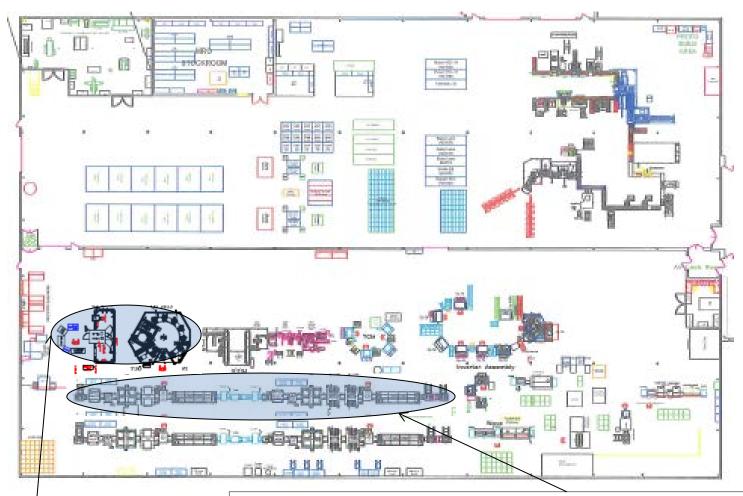
**Sealant Cure Station** 



Robotic placement: 100% Electrical verification, Leak Testing, Laser mark, Unload, Pack-out



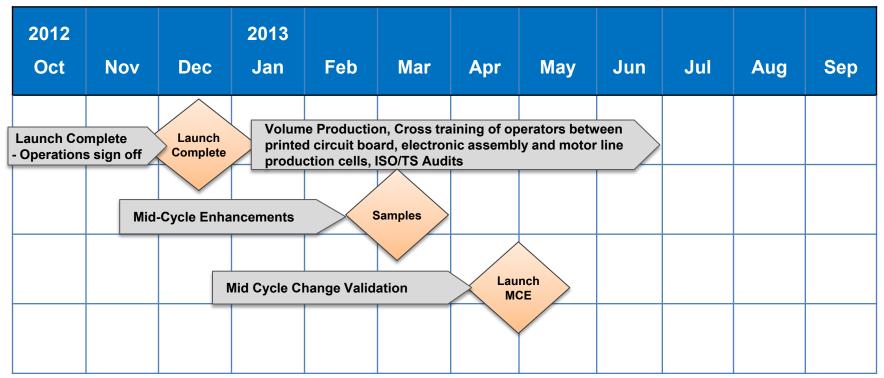
# **Approach: Grand Blanc Plant Layout To Support Added BSM & CSB Production**



2<sup>nd</sup> SMD Line to Support BSM program (Target install Q2 '14)

Final Assembly – BSM/CSB (2 separate lines) Target Installation Q4 2013

# Future Work: FY 2013 Activity Plan TCM & PCM



#### **Go, No-Go, Decision Points:**

Pass Validation Testing for Mid-Cycle Enhancements to Robustness & Productivity New Software Functions Validated at component and vehicle level

#### **Challenges or Barriers:**

Final software feature implementation timing Validation Mid-Cycle Enhancements in time for next model year production Maintaining cost position at reduced volume forecasts for 2012-2013

## Future Work: FY 2013 Activity Plan – Hybrid Controller & Battery Control Modules

| 2012                          |               |               | 2013         |            |              |          |       |              |             |          |        |
|-------------------------------|---------------|---------------|--------------|------------|--------------|----------|-------|--------------|-------------|----------|--------|
| Oct                           | Nov           | Dec           | Jan          | Feb        | Mar          | Apr      | May   | Jun          | Jul         | Aug      | Sep    |
| Hybric                        | l Cont        | roller        |              |            |              |          |       |              |             |          |        |
|                               | I, Test, & Aı |               | PPAP         | }          |              |          |       |              |             |          |        |
|                               |               |               |              |            |              |          |       |              |             |          |        |
|                               | PV            | / Testing, PI | PAP & Laun   | ch Complet | e            | Launch   | V     |              | on, Cross t | _        |        |
|                               |               | - Ope         | rations sign | off        |              | Complete |       |              |             | assembly | cells, |
|                               |               |               |              |            |              |          | Ungoi | ng Quality   | & ISO/TS A  | uaits    |        |
| Hybrid Battery Control Module |               |               |              |            |              |          |       |              |             |          |        |
|                               |               |               |              | DV Build   | , Test, & An | alysis   |       | DV<br>Finish |             |          |        |
|                               |               |               |              |            | · ·          | 1        |       | FIIIISII     |             |          |        |
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#### Go, No-Go, Decision Points:

**Hybrid Controller:** 

Launch Readiness for April start of production

**Battery Controller:** 

**Design Validation Completed** 

#### **Challenges or Barriers:**

Hybrid Controller:

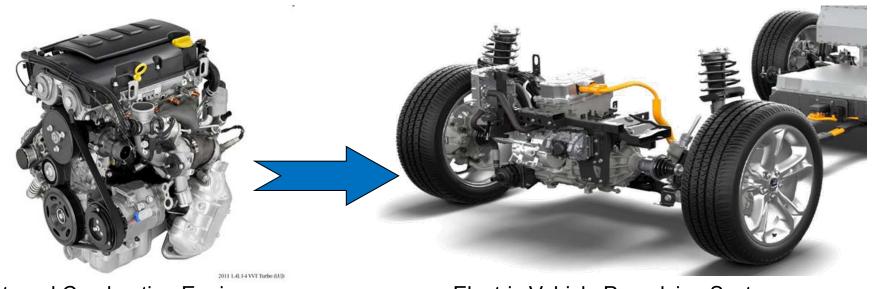
Run at Rate to required production volumes

Battery Controller:

Design Validation Monitoring equipment and laboratory readiness

## **Technical Back-Up Slides**

## **Electric Drive Component Functionality**



Internal Combustion Engine

Electric Vehicle Propulsion System

### Electric propulsion system & controller functions

- Converts electric energy to mechanical energy and vice versa
- Controllers for Battery Monitoring, Torque & Vehicle Management
- Enables Zero emission battery and fuel cell electric vehicles (EV)
- Improves efficiency & reduce emissions in hybrids (HEV & PHEV)
- Flexible powertrains with power electronics and advanced motors
- Enable readiness for future fuel cell electric drive technologies

## **Accomplishment: Integrated Inverter**



#### Description

 The Inverter provides up to 120 kW peak power to an electrical motor. With Magna E-Car Systems proprietary motor control algorithm, the Inverter accurately controls electric motor torque and power flow.

#### Features/Specifications

- Directly mounted on electric motor
- Compact and robust design for automotive reliability
- High power density
- State-of-the-art power electronics
- Optimized software and controls for efficient and accurate motor torque generation
- Integrated 3-circuit high voltage DC distribution
- Liquid-cooled
- High-speed CAN interface
- Specifications

Input voltage range: 260V to 400V

Peak power: 120 kWPeak Efficiency: >94%Peak current: 400 ArmsMaximum efficiency: 98%



#### Key Benefits



**Green Technologies** 



Safety





#### Contact

Name: Zhao Zilai Phone: (248) 265-4461



## **Accomplishment: Chassis Motor**



#### Description

 The Chassis Motor is an Interior Permanent Magnet Synchronous Machine (IPMSM) designed for electric and hybrid vehicle application traction drives. This highly efficient and quiet motor is wellsuited for both primary and auxiliary vehicle propulsion systems.

#### Features/Specifications

- Scalable from 75kW to 150kW design
- Modular to accommodate various transmissions
- Water-cooled for high continuous power ratings
- Capable of providing a high level of regenerative braking
- Low-cost housing design
- Integrated MCU mounting
- Smooth, quiet operation
- 100kW Motor Specifications

Peak Power: 100 kW
Peak Torque: 282 Nm
Continuous Power: 45 kW
Continuous Torque: 150 Nm
Maximum Speed: 10,000 rpm

Peak Efficiency: 97%



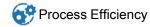
#### Key Benefits



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**Fuel Efficiency** 



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## **Accomplishment: PowerPlant System**



#### Description

Integrated **Traction Motor and Inverter** with proprietary Motor Control Software having a Controller Area Network interface to the vehicle for a turn-key motor drive system. The design mates with a coaxial or offset transmission, which is separately supplied.

#### Features/Specifications

#### **Traction Motor**

- Peak Power: 105 kWPeak Torque: 282 NmContinuous Power: 45 kW
- Continuous Torque: 150 NmMaximum Speed: 10,000 rpm
- · Peak Efficiency: 97%
- Water-cooled for high continuous power ratings
- Reduced wiring & EMI with integrated Inverter
- · Provides full regenerative braking capability
- Production Validated with automated assembly

#### Inverter

- Input voltage range: 250V to 420V
- Peak power: 120 kWPeak Efficiency: >94%Peak current: 400 Arms
- Maximum efficiency: 98%
- Compact and robust design for reliability
- High power density
- Optimized software and controls for efficient and accurate motor torque generation
- Integrated 3-circuit high voltage DC distribution
- Liquid-cooled
- High-speed CAN interface

## Contact

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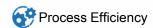
#### Key Benefits



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**Fuel Efficiency** 





## **Accomplishment: PowerPlant System** with Coaxial Gearbox



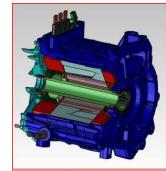
#### Description

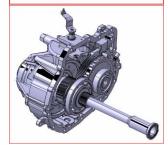
Magna's integrated electric Drive with fully integrated motor module and park lock system provides efficient construction with modular design to adapt to various layouts/ratio requirements.

#### Features/Specifications

- Integrated motor/gearbox, with co-axial layout and on-board Motor Controller
- 2 Stage Helical Gearing for compact gearbox
  - Ratio's 5.27, 6.34 & 7.82
- IPM Motor (260mm Dia)
  - Power/Torque
    - 103kW/245Nm Peak 30 sec duration
    - 45kW/150Nm Continuous
  - Speed
    - 10,000 rpm max. unloaded
    - 8,800 rpm loaded
- Liquid-Cooled 8l/min. 70°C inlet
- Direct Cable Park lock actuation with position feedback









#### **Key Benefits**



Green Technologies Process Efficiency





Vehicle Performance



Fuel Efficiency

#### Contact

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## **Accomplishment: PowerPlant System** with Offset Gearbox



Description

Magna integrated electric Drive with fully integrated motor module and park lock system.

#### Features/Specifications

- Integrated motor/gearbox with off-set layout for low hood line
- 2 Stage Helical Gearing for compact gearbox
  - Ratio 10.23:1
  - Mass 37kg
- **IPM Motor**

#### Power/Torque

- 105kW/282Nm Peak 30sec
- 45kW/ 150Nm Continuous

#### Speed

- 10,000 rpm Max. Operating speed
- · 8,800 rpm speed under load
- Liquid-Cooled 8l/min. 70°C inlet
- Direct Cable Park lock actuation with position feedback

#### **Key Benefits**



Green Technologies Process Efficiency





Vehicle Performance ( Fuel Efficiency



#### Contact

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## **Accomplishment: Stand Alone Inverter**



#### Description

The Inverter provides up to 120 kW peak power to an electrical motor. With Magna E-Car Systems proprietary motor control algorithm, the inverter accurately controls electric motor torque and power flow.

#### Features/Specifications

- Directly mounted on electric motor
- Compact and robust design for automotive reliability
- High power density
- State-of-the-art power electronics
- Optimized software and controls for efficient and accurate motor torque generation
- Integrated 3-circuit high voltage DC distribution
- Liquid-cooled
- High-speed CAN interface
- Specifications
- Input voltage range: 260V to 400V
- Peak power: 120 kWPeak Efficiency: >94%Peak current: 400 Arms
- Maximum efficiency: 98%



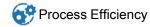
#### **Key Benefits**



Green Technologies



**Fuel Efficiency** 



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## Accomplishment: Vehicle Control Unit (VCU) M MAGNA



#### Description

The Vehicle Control Unit functions as the master controller in hybrid and electric vehicles. It is responsible for reading driver input and determining the required wheel torque, while also monitoring safety systems and providing thermal and energy management.

#### Features/Specifications

- Redundant processor safety strategy
- Low-level hardware/software interface layer
- Optional Magna-supplied vehicle control software
- Calibration over CCP or ETK
- 6-16VDC operating voltage
- 3 CAN interfaces, 1 LIN interface
- Over 66 channels of I/O
- OBD on all I/O
- 198-way connector



#### **Key Benefits**



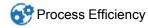
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#### Contact

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## **Progress: Power Electronics Lab Upgrades**



















# **Progress: Dynamometer Upgrades Motors and Controls Testing**

| Test<br>Cell | Test Properties |        | Status of Test Properties  |  |  |
|--------------|-----------------|--------|--|--|--|
| 1            | Dyno_300        | 224 kW | Cell upgrade to 100kW Dyno Operational for functional testing. Used for Motor Controls Development & Verification  |  |  |
| 2            | Dyno_300        | 224 kW | Cell upgrade to 100kW Dyno Operational for functional testing. Used for Motor Controls Development & Verification. |  |  |
| 3            | Dyno_350A       | 350 kW | Cell upgrade to 350kW Dyno Used for high power Motor Controls Development and Verification.                        |  |  |
| 4            | Dyno_350B       | 350 kW | Cell upgrade to 350kW Dyno Used for high power Motor Controls Development and Verification.                        |  |  |
| 5            | Dyno_5          | N/A    | High Speed Characterization Dyno   |  |  |



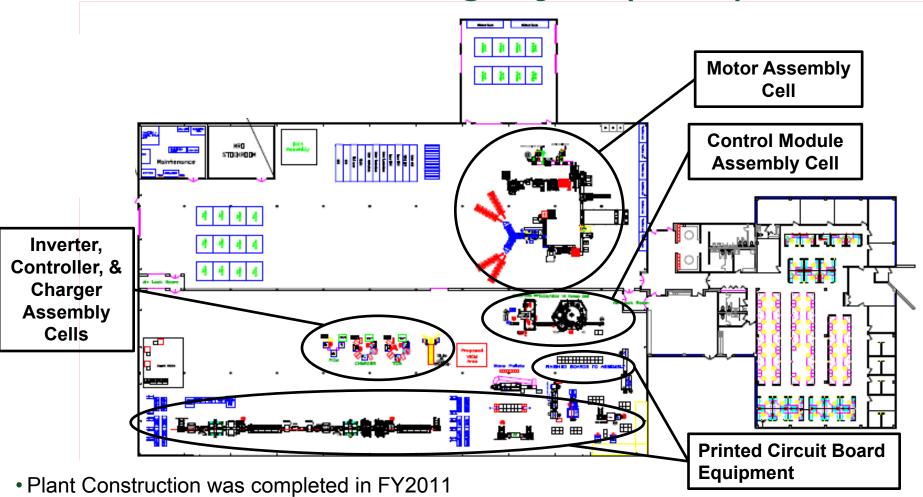






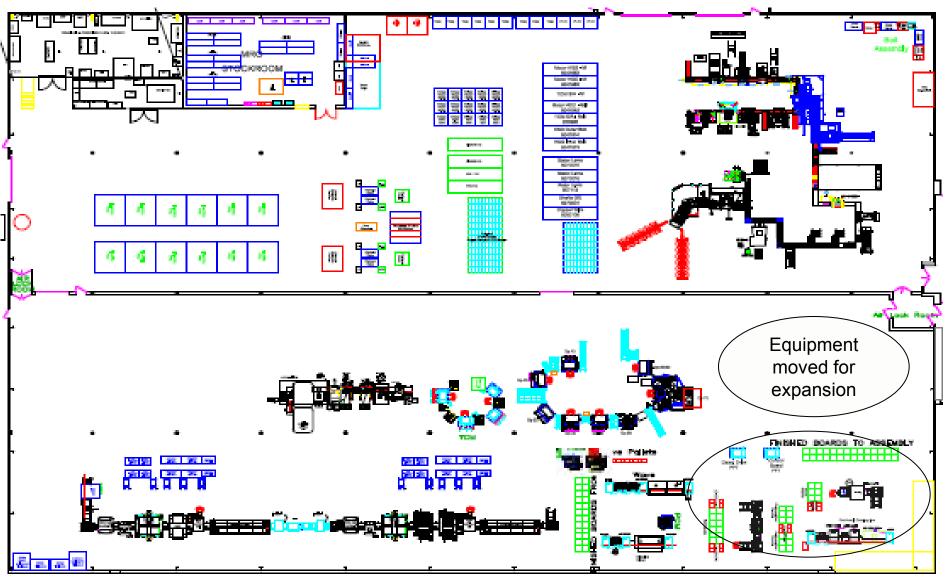


## Progress: Grand Blanc, Michigan Manufacturing Layout (GBEV)



- Process Validation (PV) Build completed FY2012
- Tooling Trials (TT) Completed FY2012
- Production Launched Currently in Mass Production

## **2012 Production Flow Improvements**



straight line process flow instituted for efficient product flow